CSCI 420 Computer Graphics
Lecture 14

Rasterization

Scan Conversion
Antialiasing
[Angel Ch. 6]

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Rasterization (scan conversion)

• Final step in pipeline: rasterization
• From screen coordinates (float) to pixels (int)
• Writing pixels into frame buffer
• Separate buffers:
  – depth (z-buffer),
  – display (frame buffer),
  – shadows (stencil buffer),
  – blending (accumulation buffer)
Rasterizing a line
Digital Differential Analyzer (DDA)

• Represent line as

\[ y = mx + h \]  
where \[ m = \frac{y_2 - y_1}{x_2 - x_1} = \frac{\Delta y}{\Delta x} \]

• Then, if \( \Delta x = 1 \) pixel, we have \( \Delta y = m \Delta x = m \)
Digital Differential Analyzer

- Assume `write_pixel(int x, int y, int value)`
  
  ```c
  for (i = x1; i <= x2; i++)
  { y += m;
    write_pixel(i, round(y), color);
  }
  ```

- Problems:
  - Requires floating point addition
  - Missing pixels with steep slopes: slope restriction needed
Digital Differential Analyzer (DDA)

- Assume $0 \leq m \leq 1$
- Exploit symmetry
- Distinguish special cases

But still requires floating point additions!
Bresenham’s Algorithm I

- Eliminate floating point addition from DDA
- Assume again $0 \leq m \leq 1$
- Assume pixel centers halfway between integers
Bresenham’s Algorithm II

• Decision variable $a - b$
  – If $a - b > 0$ choose lower pixel
  – If $a - b \leq 0$ choose higher pixel

• Goal: avoid explicit computation of $a - b$

• Step 1: re-scale $d = (x_2 - x_1)(a - b) = \Delta x(a - b)$

• $d$ is always integer
Bresenham’s Algorithm III

• Compute \( d \) at step \( k+1 \) from \( d \) at step \( k \)!

• Case: \( j \) did not change (\( d_k > 0 \))
  – \( a \) decreases by \( m \), \( b \) increases by \( m \)
  – \( (a - b) \) decreases by \( 2m = 2(\Delta y/\Delta x) \)
  – \( \Delta x(a-b) \) decreases by \( 2\Delta y \)
Bresenham’s Algorithm IV

• Case: j did change \((d_k \leq 0)\)
  – a decreases by \(m-1\), b increases by \(m-1\)
  – \((a - b)\) decreases by \(2m - 2 = 2(\Delta y/\Delta x - 1)\)
  – \(\Delta x(a-b)\) decreases by \(2(\Delta y - \Delta x)\)
Bresenham’s Algorithm V

• So \( d_{k+1} = d_k - 2\Delta y \) if \( d_k > 0 \)
• And \( d_{k+1} = d_k - 2(\Delta y - \Delta x) \) if \( d_k \leq 0 \)
• Final (efficient) implementation:

```c
void draw_line(int x1, int y1, int x2, int y2) {
    int x, y = y0;
    int twice_dx = 2 * (x2 - x1), twice.dy = 2 * (y2 - y1);
    int twice_dy_minus_twice_dx = twice_dy - twice_dx;
    int d = twice_dx / 2 - twice_dy;

    for (x = x1 ; x <= x2 ; x++) {
        write_pixel(x, y, color);
        if (d > 0) d -= twice_dy;
        else {y++; d -= twice_dy_minus_twice_dx ;}
    }
}
```
Bresenham’s Algorithm VI

- Need different cases to handle $m > 1$
- Highly efficient
- Easy to implement in hardware and software
- Widely used
Outline

• Scan Conversion for Lines
• Scan Conversion for Polygons
• Antialiasing
Scan Conversion of Polygons

• Multiple tasks:
  – Filling polygon (inside/outside)
  – Pixel shading (color interpolation)
  – Blending (accumulation, not just writing)
  – Depth values (z-buffer hidden-surface removal)
  – Texture coordinate interpolation (texture mapping)

• Hardware efficiency is critical
• Many algorithms for filling (inside/outside)
• Much fewer that handle all tasks well
Filling Convex Polygons

- Find top and bottom vertices
- List edges along left and right sides
- For each scan line from bottom to top
  - Find left and right endpoints of span, $x_l$ and $x_r$
  - Fill pixels between $x_l$ and $x_r$
  - Can use Bresenham’s algorithm to update $x_l$ and $x_r$
Concave Polygons: Odd-Even Test

• Approach 1: odd-even test
• For each scan line
  – Find all scan line/polygon intersections
  – Sort them left to right
  – Fill the interior spans between intersections
• Parity rule: inside after an odd number of crossings
Edge vs Scan Line Intersections

- Brute force: calculate intersections explicitly
- Incremental method (Bresenham’s algorithm)
- Caching intersection information
  - Edge table with edges sorted by $y_{\text{min}}$
  - Active edges, sorted by x-intersection, left to right
- Process image from smallest $y_{\text{min}}$ up
Concave Polygons: Tessellation

• Approach 2: divide non-convex, non-flat, or non-simple polygons into triangles

• OpenGL specification
  – Need accept only simple, flat, convex polygons
  – Tessellate explicitly with tessellator objects
  – Implicitly if you are lucky

• Most modern GPUs scan-convert only triangles
Flood Fill

- Draw outline of polygon
- Pick color seed
- Color surrounding pixels and recurse
- Must be able to test boundary and duplication
- More appropriate for drawing than rendering
Outline

- Scan Conversion for Lines
- Scan Conversion for Polygons
- Anti-aliasing
Aliasing

- Artifacts created during scan conversion
- Inevitable (going from continuous to discrete)
- Aliasing (name from digital signal processing): we sample a continues image at grid points
- Effect
  - Jagged edges
  - Moire patterns

Moire pattern from sandlotscience.com
More Aliasing

No antialiasing
Antialiasing for Line Segments

• Use area averaging at boundary

(a) is aliased; (b) is antialiased
• (c) is aliased + magnified
• (d) is antialiased + magnified
Antialiasing by Supersampling

- Mostly for off-line rendering (e.g., ray tracing)
- Render, say, 3x3 grid of mini-pixels
- Average results using a filter
- Can be done adaptively
  - Stop if colors are similar
  - Subdivide at discontinuities

\[ \text{one pixel} \]
Supersampling Example

• Other improvements
  – Stochastic sampling: avoid sample position repetitions
  – Stratified sampling (jittering): perturb a regular grid of samples
Temporal Aliasing

- Sampling rate is frame rate (30 Hz for video)
- Example: spokes of wagon wheel in movies
- Solution: supersample in time and average
  - Fast-moving objects are blurred
  - Happens automatically with real hardware (photo and video cameras)
    - Exposure time is important (shutter speed)
  - Effect is called motion blur
Wagon Wheel Effect

Source: YouTube
Motion Blur Example

Achieve by stochastic sampling in time

T. Porter, Pixar, 1984
16 samples / pixel / timestep
Depth of Field

Wide depth of field

Narrow depth of field

digital-photography-school.com
Summary

• Scan Conversion for Polygons
  – Basic scan line algorithm
  – Convex vs concave
  – Odd-even rules, tessellation

• Antialiasing (spatial and temporal)
  – Area averaging
  – Supersampling
  – Stochastic sampling